

# Almost-sure hedging under permanent price impact

Y.Zou

Université Paris Dauphine

April 20, 2016

- 1 Introduction
- 2 Process dynamics and hedging problems
  - Impact rule and continuous trading dynamics
  - Hedging problem: covered options
- 3 Super-replication under gamma constraint
  - Statement of pricing PDE
  - Viscosity solution of the pricing PDE

- Objective:

- Objective:
  - ① Consider a pricing model with *impact* and *liquidity cost*.

- Objective:
  - ① Consider a pricing model with **impact** and **liquidity cost**.
  - ② Not high frequency (no bid-ask spread), but still impact on prices.

- Objective:
  - ① Consider a pricing model with **impact** and **liquidity cost**.
  - ② Not high frequency (no bid-ask spread), but still impact on prices.
  - ③ **Permanent** impact.

- Objective:
  - ① Consider a pricing model with **impact** and **liquidity cost**.
  - ② Not high frequency (no bid-ask spread), but still impact on prices.
  - ③ **Permanent** impact.
  
- Approach:

- Objective:
  - ① Consider a pricing model with **impact** and **liquidity cost**.
  - ② Not high frequency (no bid-ask spread), but still impact on prices.
  - ③ **Permanent** impact.
  
- Approach:
  - ① Define a **continuous time trading dynamics** from a discrete time rule.



- Objective:
  - ① Consider a pricing model with **impact and liquidity cost**.
  - ② Not high frequency (no bid-ask spread), but still impact on prices.
  - ③ **Permanent** impact.
  
- Approach:
  - ① Define a **continuous time trading dynamics** from a discrete time rule.
  - ② Provide the **PDE characterization**: **stochastic target tool**.

# Impact rule & Trading signal

Basic rule: an order  $\delta$  moves the price by

$$X_{t-} \longrightarrow X_t = X_{t-} + \delta f(X_{t-}),$$

and costs

$$\delta X_{t-} + \frac{1}{2} \delta^2 f'(X_{t-}) = \delta \left( \frac{X_{t-} + X_t}{2} \right).$$

# Impact rule & Trading signal

Basic rule: an order  $\delta$  moves the price by

$$X_{t-} \longrightarrow X_t = X_{t-} + \delta f(X_{t-}),$$

and costs

$$\delta X_{t-} + \frac{1}{2} \delta^2 f(X_{t-}) = \delta \left( \frac{X_{t-} + X_t}{2} \right).$$

A trading signal is an Itô process of the form

$$Y = Y_0 + \int_0^\cdot b_s ds + \int_0^\cdot a_s dW_s.$$

# Discrete trading dynamics

- Trade at times  $t_i^n = iT/n$  the quantity  $\delta_{t_i^n}^n = Y_{t_i^n} - Y_{t_{i-1}^n}$ .

# Discrete trading dynamics

- Trade at times  $t_i^n = iT/n$  the quantity  $\delta_{t_i^n}^n = Y_{t_i^n} - Y_{t_{i-1}^n}$ .
- The stock price evolves according to

$$X = X_{t_i^n} + \int_{t_i^n}^{\cdot} \sigma(X_s) dW_s$$

between two trades.(can add a drift or be multivariate.)

# Discrete trading dynamics

- Trade at times  $t_i^n = iT/n$  the quantity  $\delta_{t_i^n}^n = Y_{t_i^n} - Y_{t_{i-1}^n}$ .
- The stock price evolves according to

$$X = X_{t_i^n} + \int_{t_i^n}^{\cdot} \sigma(X_s) dW_s$$

between two trades.(can add a drift or be multivariate.)

- Dynamics of the wealth and of the asset: discrete trading and pass to the limit.

# Continuous trading dynamics

Passing to the limit  $n \rightarrow \infty$ , we have the following convergence in  $\mathbf{S}_2$

$$Y = Y_0 + \int_0^\cdot b_s ds + \int_0^\cdot a_s dW_s$$

$$X = X_0 + \int_0^\cdot \sigma(X_s) dW_s + \int_0^\cdot f(X_s) dY_s + \int_0^\cdot (\mu + a_s \sigma f')(X_s) ds$$

$$V = V_0 + \int_0^\cdot Y_s dX_s + \frac{1}{2} \int_0^\cdot a_s^2 f(X_s) ds,$$

at a speed  $\sqrt{n}$ , where

$$V = \text{cash part} + YX = \text{“portfolio value”}.$$

# Super-replication under gamma constraint

- Covered options:  
No initial/final market impact.



# Super-replication under gamma constraint

- Covered options:  
No initial/final market impact.
- Super-replication:  
The minimum initial total wealth to cover the final payoff in almost sure sense.

# Super-replication under gamma constraint

- Covered options:  
No initial/final market impact.
- Super-replication:  
The minimum initial total wealth to cover the final payoff in almost sure sense.
- Gamma constraint:  
Re-write the dynamics of  $Y$  as below:

$$dY = a dW + b dt = \gamma^a(X) dX + \mu_Y^{a,b}(X) dt$$

with  $\gamma^a = a/(\sigma + af)$ . Then  $\gamma^a(X)$  is bounded by some function.

Super-hedging price under gamma constraint:

$$v(t, x) := \inf \{v = c + yx : (c, y) \in \mathbb{R}^2 \text{ s.t. } \mathcal{G}^\gamma(t, x, v, y) \neq \emptyset\}$$

where  $\mathcal{G}^\gamma(t, x, v, y)$  is the set of  $(a, b)$  s.t.  $\phi := (y, a, b)$  satisfies:

$$V_T^{t,x,v,\phi} \geq g(X_T^{t,x,\phi}), \quad \text{and} \quad \gamma^a(X) \leq \bar{\gamma}(X)$$

with  $f\bar{\gamma} < 1 - \epsilon$ ,  $\epsilon > 0$ .

# Informal derivation

If we follow the delta-hedging rule:

$$V = v(\cdot, X) \text{ , and } Y = \partial_x v(\cdot, X)$$

# Informal derivation

If we follow the delta-hedging rule:

$$V = v(\cdot, X) \text{ , and } Y = \partial_x v(\cdot, X)$$

Equating the  $dt$  terms on  $V = v(\cdot, X)$  &  $dX$  terms on  $Y = \partial_x v(\cdot, X)$ :

$$\begin{aligned} \frac{1}{2}a^2 f(X) &= \partial_t v(\cdot, X) + \frac{1}{2}(\sigma + af)^2(X) \partial_{xx}^2 v(\cdot, X) \\ \gamma^a &= \partial_{xx}^2 v(\cdot, X) \end{aligned}$$

# Informal derivation

If we follow the delta-hedging rule:

$$V = v(\cdot, X) \text{ , and } Y = \partial_x v(\cdot, X)$$

Equating the  $dt$  terms on  $V = v(\cdot, X)$  &  $dX$  terms on  $Y = \partial_x v(\cdot, X)$ :

$$\begin{aligned} \frac{1}{2}a^2 f(X) &= \partial_t v(\cdot, X) + \frac{1}{2}(\sigma + af)^2(X) \partial_{xx}^2 v(\cdot, X) \\ \gamma^a &= \partial_{xx}^2 v(\cdot, X) \end{aligned}$$

By definition of  $\gamma^a$  and some calculate:

$$\left[ -\partial_t v - \frac{1}{2} \frac{\sigma^2}{(1 - f \partial_{xx}^2 v)} \partial_{xx}^2 v \right] (\cdot, X) = 0$$

Gamma constraint insures the non-singularity of the PDE.

# Pricing PDE and Terminal condition

- Pricing PDE: on  $[0, T) \times \mathbb{R}$

$$\begin{aligned} F[v_{\bar{\gamma}}](t, x) &:= \min \left\{ -\partial_t v_{\bar{\gamma}} - \frac{1}{2} \frac{\sigma^2}{(1 - f \partial_{xx}^2 v_{\bar{\gamma}})} \partial_{xx}^2 v_{\bar{\gamma}}, \bar{\gamma} - \partial_{xx}^2 v_{\bar{\gamma}} \right\} \\ &= 0 \end{aligned}$$

- Propagation of the gamma constraint to the boundary:

$$v_{\bar{\gamma}}(T-, \cdot) = \hat{g} \text{ on } \mathbb{R}$$

where  $\hat{g}$  is the smallest (viscosity) super-solution of

$$\min\{\varphi - g, \bar{\gamma} - \partial_{xx}^2 \varphi\} = 0$$

## Theorem (Geometric Dynamic Programming Principle)

*If  $V_0 > v(0, X_0)$ , then there exists  $(a, b, Y_0)$  such that*

$$V_\theta \geq v(\theta, X_\theta)$$

*for any stopping time  $\theta \in [0, T]$ .*

Result: A super-solution  $\underline{v}_{\bar{\gamma}} \leq v_{\bar{\gamma}}$ . cf. N.Touzi, M.Soner.



# Sub-solution property: shaken operator

Objective: Construct a solution  $\bar{v}_{\bar{\gamma}} \geq v_{\bar{\gamma}}$ .

## Theorem

Define the shaken operator

$$F^\epsilon[\varphi](t, x) := \min_{x' \in B_\epsilon(x)} \min \left\{ -\partial_t \varphi + \frac{\sigma^2(x')}{2(1 - f(x')\partial_{xx}^2 \varphi)}, \bar{\gamma}(x') - \partial_{xx}^2 \varphi \right\} (t, x)$$

then  $\forall \epsilon > 0$ ,  $\exists \bar{v}_{\bar{\gamma}}^\epsilon$  the unique continuous viscosity solution of

$$F^\epsilon[\varphi](t, x) \mathbb{1}_{[0, T)} + [\varphi - (\hat{g} + \epsilon)] \mathbb{1}_{\{T\}} = 0$$

Moreover,  $\bar{v}_{\bar{\gamma}}^\epsilon \geq \hat{g} + \epsilon/2$  on  $[T - c_\epsilon, T] \times \mathbb{R}$ .

# Sub-solution property: shaken operator

Objective: Construct a solution  $\bar{v}_{\bar{\gamma}} \geq v_{\bar{\gamma}}$ .

# Sub-solution property: shaken operator

Objective: Construct a solution  $\bar{v}_{\bar{\gamma}} \geq v_{\bar{\gamma}}$ .

By the stability of viscosity solution:

$$\bar{v}_{\bar{\gamma}}^\epsilon \rightarrow \bar{v}_{\bar{\gamma}}, \quad \text{as } \epsilon \rightarrow 0$$

where  $\bar{v}_{\bar{\gamma}}$  is the unique viscosity solution of

$$F[\varphi](t, x) \mathbb{1}_{[0, T)} + (\varphi - \hat{g}) \mathbb{1}_{\{T\}} = 0$$

# Sub-solution property: shaken operator

Objective: Construct a solution  $\bar{v}_{\bar{\gamma}} \geq v_{\bar{\gamma}}$ .

By the stability of viscosity solution:

$$\bar{v}_{\bar{\gamma}}^\epsilon \rightarrow \bar{v}_{\bar{\gamma}}, \quad \text{as } \epsilon \rightarrow 0$$

where  $\bar{v}_{\bar{\gamma}}$  is the unique viscosity solution of

$$F[\varphi](t, x) \mathbb{1}_{[0, T)} + (\varphi - \hat{g}) \mathbb{1}_{\{T\}} = 0$$

Remain to prove:  $\bar{v}_{\bar{\gamma}} \geq v_{\bar{\gamma}}$ .

# Sub-solution property: regularization

## Theorem

For  $\psi \in C^\infty$ , define  $\psi_\delta = \delta^{-2}\psi(\cdot/\delta)$ . Then  $\bar{v}_{\bar{\gamma}}^{\epsilon,\delta} := \bar{v}_{\bar{\gamma}}^\epsilon \star \psi_\delta$  is a super-solution of

$$F[\bar{v}_{\bar{\gamma}}^{\epsilon,\delta}](t, x) \mathbb{1}_{[\delta, T)} + (\bar{v}_{\bar{\gamma}}^{\epsilon,\delta} - \hat{g}) \mathbb{1}_{\{T\}} = 0$$

Then  $Y := \partial_x \bar{v}_{\bar{\gamma}}^{\epsilon,\delta}(\cdot, X)$  provides a super-hedging strategy, i.e.  $\bar{v}_{\bar{\gamma}}^{\epsilon,\delta} \geq v_{\bar{\gamma}}$ .

Moreover,  $\lim_{\epsilon, \delta \rightarrow 0} \bar{v}_{\bar{\gamma}}^{\epsilon,\delta} = \bar{v}_{\bar{\gamma}}$ .

Conclusion:

$$\bar{v}_{\bar{\gamma}} = \lim_{\epsilon, \delta \rightarrow 0} \bar{v}_{\bar{\gamma}}^{\epsilon,\delta} \geq v_{\bar{\gamma}} \geq \underline{v}_{\bar{\gamma}} \geq \bar{v}_{\bar{\gamma}}$$

# Numerical res: Bachelier model with constant impact

Model:  $dX_t = 0.2 dW_t$ ; Butterfly:  $g(x) = (x + 1)^+ - 2x^+ + (x - 1)^+$

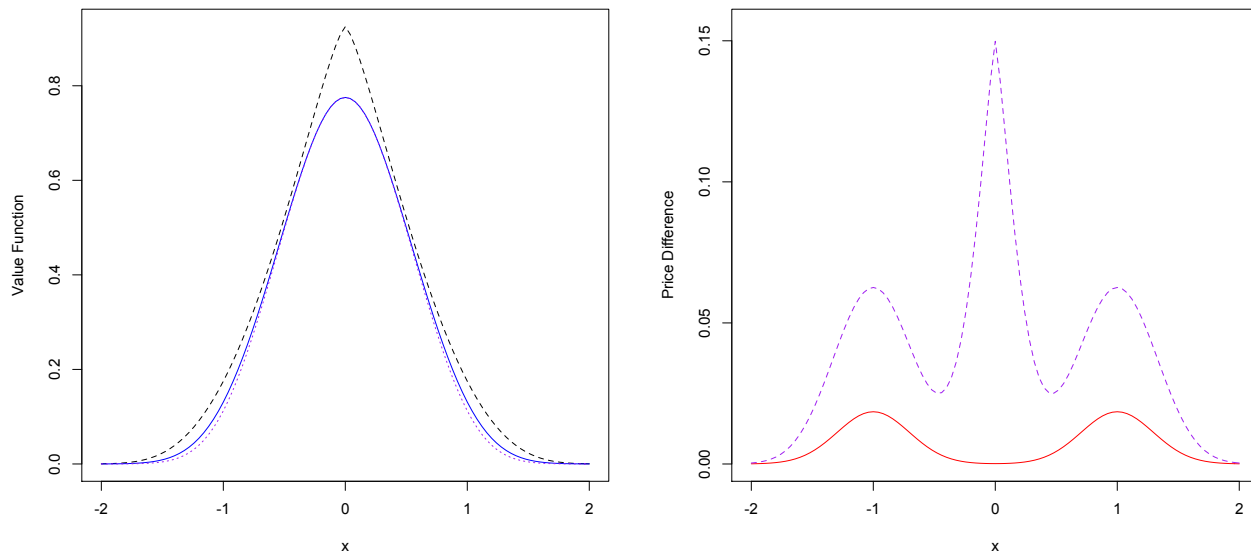


Figure 1: Left: Super-hedging price. Dashed line:  $\lambda = 0.5$ ,  $\bar{\gamma} = 1.75$ ; solid line:  $\lambda = 0$ ,  $\bar{\gamma} = 1.75$ ; dotted line:  $\lambda = 0$ ,  $\bar{\gamma} = +\infty$ . Right: Difference with the price associated to  $\lambda = 0$ ,  $\bar{\gamma} = +\infty$ . Dashed line:  $\lambda = 0.5$ ,  $\bar{\gamma} = 1.75$ ; solid line:  $\lambda = 0$ ,  $\bar{\gamma} = 1.75$ .

*Thank you very much!*