

Rare event simulation related to financial risks

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Introduction

Questions:

- estimate $p := \mathbb{P}(X \in A)$ and $\mathbb{E}(\varphi(X)|X \in A)$ when $p < 10^{-5}$
- sample from $X|X \in A$
- compute sensitivity like $\frac{\partial_{\theta} \mathbb{E}(\varphi(X^{\theta}) \mathbf{1}_{X^{\theta} \in A})}{\mathbb{E}(\varphi(X^{\theta}) \mathbf{1}_{X^{\theta} \in A})}$

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Simple Monte Carlo: $(X_n)_{n \geq 1}$ i.i.d. copies of X , by CLT

$$\sqrt{N}(S_N - \mathbb{P}(X \in A)) \rightarrow \mathcal{N}(0, p(1-p))$$

where $S_N = \frac{1}{N} \sum_{k=1}^N \mathbf{1}_{\{X_k \in A\}}$

95% confidence interval: $(S_N - 1.96\sqrt{\frac{p(1-p)}{N}}, S_N + 1.96\sqrt{\frac{p(1-p)}{N}})$

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But $\frac{\sqrt{p(1-p)}}{\sqrt{Np}} \approx \frac{1}{\sqrt{Np}}$ is large for small p , which means large relative error.

Importance sampling

Classic technique: importance sampling

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Example: X follows $\mathcal{N}(0, 1)$, to estimate $\mathbb{P}(X > 5)$, we define another probability \mathbb{Q} by

$$\frac{d\mathbb{Q}}{d\mathbb{P}}(X) = \exp\left\{aX - \frac{1}{2}a^2\right\}$$

under \mathbb{Q} X follows $\mathcal{N}(a, 1)$, so with $a = 5$ and (X_n) i.i.d copies of $\mathcal{N}(5, 1)$

$$\mathbb{P}(X > 5) = \mathbb{E}^{\mathbb{Q}}\left(1_{X>5} \frac{d\mathbb{P}}{d\mathbb{Q}}\right) \approx \frac{1}{N} \sum_{n=1}^N 1_{X_n>5} \frac{d\mathbb{P}}{d\mathbb{Q}}(X_n)$$

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Unfortunately, in general case, it's not easy to design such a new probability. When X is a complicated random system (stochastic process, random matrix, random graph, etc), new techniques need to be found.

Reformulation using conditional probabilities

Classic technique: importance sampling. However, in general it is difficult to implement this method.

We define a series of nested subsets of the entire probability space \mathbb{S}

$$\mathbb{S} := A_0 \supset \cdots \supset A_k \supset \cdots \supset A_n := A$$

$$\mathbb{P}(X \in A) = \prod_{k=1}^n \mathbb{P}(X \in A_k | X \in A_{k-1})$$

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Existing methods: splitting/restart, interacting particles system(IPS).
We propose an new method using the ergodicity of Markov chain

Definition of shaking transformation

Definition: Given a random object X (variable, process, \dots), $\mathcal{K}(\cdot)$ is a **reversible shaking transformation** for X if:

$$(X, \mathcal{K}(X)) \stackrel{d}{=} (\mathcal{K}(X), X). \quad (1)$$

We also write $\mathcal{K}(X) = K(X, Y)$, where K is deterministic and Y is independent of X

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Examples:

- If X is a standard normal variable

$$K(X, \mathbf{N}(0, 1)) = \rho X + \sqrt{1 - \rho^2} \mathbf{N}(0, 1), \quad -1 \leq \rho \leq 1$$

- If X is a standard Brownian motion

$$K(X, G') = \left(\int_0^t \rho_s dX_s + \int_0^t \sqrt{1 - \rho_s^2} dG'_s \right)_{0 \leq t \leq T}$$

Shaking with rejection and conditional invariance

Let $k \in \{0, 1, \dots, n-1\}$, define the **shaking with rejection** $\mathcal{M}_k^{\mathcal{K}}$ by

$$\mathcal{M}_k^{\mathcal{K}}(X) = \begin{cases} \mathcal{K}(X) & \text{if } \mathcal{K}(X) \in A_k \\ X & \text{if } \mathcal{K}(X) \notin A_k. \end{cases} \quad (2)$$

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Proposition (conditional invariance)

Let $k \in \{0, 1, \dots, n-1\}$. The distribution of X conditionally on $\{X \in A_k\}$ is invariant w.r.t. the random transformation $\mathcal{M}_k^{\mathcal{K}}$: i.e. for any bounded (random) measurable $\varphi : \mathbb{S} \rightarrow \mathbb{R}$, we have

$$\mathbb{E}(\varphi(\mathcal{M}_k^{\mathcal{K}}(X)) | X \in A_k) = \mathbb{E}(\varphi(X) | X \in A_k). \quad (3)$$

POP(Parallel One-Path) method

Birkhoff's theorem for ergodic Markov chain $(Z_i)_{i \geq 0}$ with a unique invariant distribution π :

$$\frac{1}{N} \sum_{i=0}^{N-1} f(Z_i) \xrightarrow{N \rightarrow +\infty} \int f d\pi \quad a.s.$$

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Given an initial position $X_{k,0} \in A_k$, we define $X_{k,i} := \mathcal{M}_k^{\mathcal{K}}(X_{k,i-1})$

$$\mathbb{E}(\varphi(X)|X \in A_k) \approx \frac{1}{N} \sum_{i=0}^{N-1} \varphi(X_{k,i})$$

With $\varphi \equiv \mathbf{1}_{A_{k+1}}$, $\mathbb{P}(X \in A_{k+1}|X \in A_k) \approx \frac{1}{N} \sum_{i=0}^{N-1} \mathbf{1}_{A_{k+1}}(X_{k,i})$

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Our estimators for each $P(X \in A_{k+1}|X \in A_k)$ can be made independent!

POP playing

convergence POP

For all finite dimension cases, we can prove POP method converges almost surely using a short proof for Markov chain's ergodicity from Asmussen and Glynn (2011)

For convergence rate(Łatuszyński et al. (2013))

$$\theta = \pi(f), \hat{\theta} = \frac{1}{N} \sum_{i=1}^N f(X_i)$$

under some stronger assumptions, there exists constant C such that

$$\mathbb{E}(\hat{\theta} - \theta)^2 \leq \frac{C}{N}$$

Explicit shaking construction

- If X is a standard normal variable

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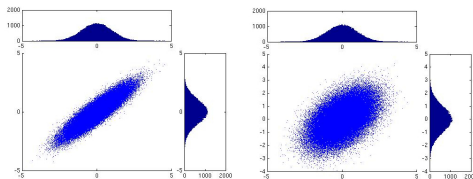


Figure: Shaking $N(0, 1)$ with $\rho = 0.9$ and $\rho = 0.5$

Explicit shaking construction

- For a Gamma distribution $Ga \sim \text{Gamma}(\alpha, \beta)$, i.e

$$\mathbb{P}(Ga \in dx) = \frac{\beta^\alpha}{\Gamma(\alpha)} x^{\alpha-1} e^{-\beta x} dx, x > 0$$

The transformation is (see Dufresne (1998))

$$K(Ga) = Ga * \text{Beta}(\alpha(1-p), \alpha p) + \text{Gamma}(\alpha p, \beta)$$

In particular, it applies for exponential variable with $\alpha = 1$

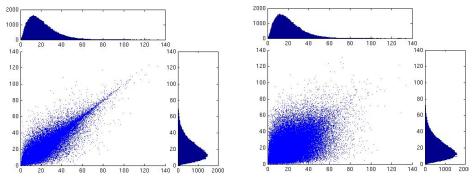


Figure: Shaking $\text{Gamma}(2.5, 0.12)$ with $p = 0.1$ and $p = 0.5$

Shaking list

- Poisson variable $P \sim \mathcal{P}(\lambda)$: $\mathcal{K}(P) = \text{Binomial}(P, p) + \mathcal{P}((1-p)\lambda)$
- Bernoulli variable $B \sim \text{Bernoulli}(q)$: $qP(1, 0) = (1-q)P(0, 1)$

$$Y \stackrel{d}{=} f(X) \implies \mathcal{K}_Y(\cdot) = f(\mathcal{K}_X(f^{-1}(\cdot)))$$

- Uniform U : $-\ln U \stackrel{d}{=} \text{Exp}(1)$
- Cauchy C : $\frac{1}{\pi} \arctan(C) + \frac{1}{2}$ is uniform
- $\chi^2(k)$ R_k : $R_k \stackrel{d}{=} 2\text{Gamma}(\frac{k}{2}, 1)$

Other shakings

- if $Y = f(X_1, X_2, \dots, X_n)$, shake Y through shaking all the X_i 's
- Metropolis-Hasting Gibbs type shaking
- Given a large number of r.v.'s, we can also only shake a randomly sampled part of them

Shaking transformation for stochastic process

- Compound Poisson process: Let $X_t = \sum_{k=1}^{N_t} Y_k$ be a $CPP(\lambda, \mu)$

$$\text{CPP decomposition: } X_t = X_t^a + X_t^b$$

where $X^a \stackrel{d}{=} CPP((1-p)\lambda, \mu)$ and $X^b \stackrel{d}{=} CPP(p\lambda, \mu)$

$$K(X, Z) = (X_t^a + Z_t)_{0 \leq t \leq T}, Z_t \stackrel{d}{=} CPP(p\lambda, \mu)$$

- Let Y be a pure jump process with inter-arrival $(A_n)_{n \geq 1}$ and $(B_n)_{n \geq 1}$, shake all the A_n 's and B_n 's \implies shake Y .
- Conditional shaking, keep inter-arrival $(A_n)_{n \geq 1}$, only shake $(B_n)_{n \geq 1}$.

Others possibilities: To shake a Levy process for example, we can apply shaking transformations for the underlying Brownian motion and compound Poisson process.

Adaptive POP method

Question: How to choose the values of intermediary levels?

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In case that no additional information is available about the model, we can choose our nested subset on the run, i.e. in an adaptive way.

We propose an adaptive version of POP method and prove it converges almost surely.

Adaptive POP playing with 50% quantile

Extreme scenario generation and sensitivity

Extreme scenario generation: recall the Markov chain defined by

$$X_{k,0} \in A_k, X_{k,i} := \mathcal{M}_k^{\mathcal{K}}(X_{k,i-1})$$

we have $\|\mathcal{L}(X_{k,i}) - X|X \in A_k\|_{TV} \rightarrow 0$

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we have $\|\mathcal{L}(X_{k,i}) - X|X \in A_k\|_{TV} \rightarrow 0$

Sensitivity: by likelihood method or Malliavin calculus, there exists some ϕ such that

$$\frac{\partial_{\theta} \mathbb{E}(\varphi(X^{\theta}) \mathbf{1}_{X^{\theta} \in A})}{\mathbb{E}(\varphi(X^{\theta}) \mathbf{1}_{X^{\theta} \in A})} = \frac{\mathbb{E}(\phi \mathbf{1}_{X^{\theta} \in A})}{\mathbb{E}(\varphi(X^{\theta}) \mathbf{1}_{X^{\theta} \in A})} = \frac{\mathbb{E}(\phi | X^{\theta} \in A)}{\mathbb{E}(\varphi(X^{\theta}) | X^{\theta} \in A)}$$

which can be evaluated using only one Markov chain

Oscillation of Orstein-Uhlenbeck process

$$dY_t = \lambda(\mu - Y_t)dt + \sigma dW_t, Y_0 = 0, \lambda = 1, \mu = 0, \sigma = 1, T = 1$$

$$\mathbb{P}(\max_{0 \leq l \leq 100} \tilde{Y}_{t_l} > 1.6 \text{ and } \min_{0 \leq l \leq 100} \tilde{Y}_{t_l} < -1.6)$$

7×10^9 MC simulation gives $[3.9709, 4.3691] \times 10^{-7}$

Set $L_i = 1.6 * (\frac{i}{5})^{1/2}$ and $A_i = (\max_{0 \leq l \leq 100} \tilde{Y}_{t_l} > L_i \text{ and } \min_{0 \leq l \leq 100} \tilde{Y}_{t_l} < -L_i)$

100 runs for each parameter:

IPS: $M = 10^5$

	mean	std	std/mean
$\rho = 0.9$	4.01e-07	1.23e-07	0.31
$\rho = 0.75$	4.10e-07	1.67e-07	0.41
$\rho = 0.5$	2.44e-07	4.76e-07	1.95

POP: $N = 10^5$

	mean	std	std/mean
$\rho = 0.9$	4.14e-07	2.68e-08	0.06
$\rho = 0.75$	4.18e-07	4.60e-08	0.11
$\rho = 0.5$	4.29e-07	1.26e-07	0.29

Oscillation of Orstein-Uhlenbeck process

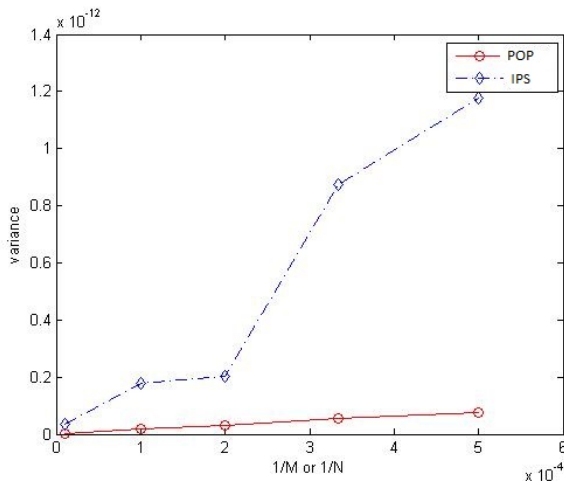


Figure: Variance for two methods

Model misspecification and robustness

Real world: σ_+ when spot is lower than past M-4, σ_- in the other case.

Trader thinks it's a constant volatility σ_- , hedging the payoff $(S_T - K)_+$ with BS. With $T = 1$, $S_0 = 10$, $\sigma_- = 0.2$, $\sigma_+ = 0.27$, $K = 10$ and $L = -2.4$, what is the probability that the trader's P&L is less than L ?

The crude Monte Carlo method with 5×10^8 simulations provides a 99% confidence interval $[2.93, 3.34] \times 10^{-6}$.

Model misspecification and robustness

$M = N = 10^5$:

with prefixed intermediary levels $L_k = \frac{k}{5} * L, k = 1, 2, 3, 4, 5$

	IPS			POP		
	mean ($\times 10^{-6}$)	std. ($\times 10^{-7}$)	std./mean	mean ($\times 10^{-6}$)	std. ($\times 10^{-7}$)	std./mean
$\rho = 0.9$	3.10	5.29	0.17	3.13	2.07	0.07
$\rho = 0.7$	3.23	13.3	0.41	3.11	3.98	0.13
$\rho = 0.5$	2.79	25.9	0.93	3.18	8.44	0.27

adaptive methods:

	IPS			POP		
	mean ($\times 10^{-6}$)	std. ($\times 10^{-7}$)	std./mean	mean ($\times 10^{-6}$)	std. ($\times 10^{-7}$)	std./mean
$\rho = 0.9$	3.06	4.95	0.16	3.18	2.42	0.08
$\rho = 0.7$	2.98	11.1	0.37	3.10	3.71	0.12
$\rho = 0.5$	2.45	23.6	0.96	3.06	7.27	0.24

Typical scenario leading to large hedging loss

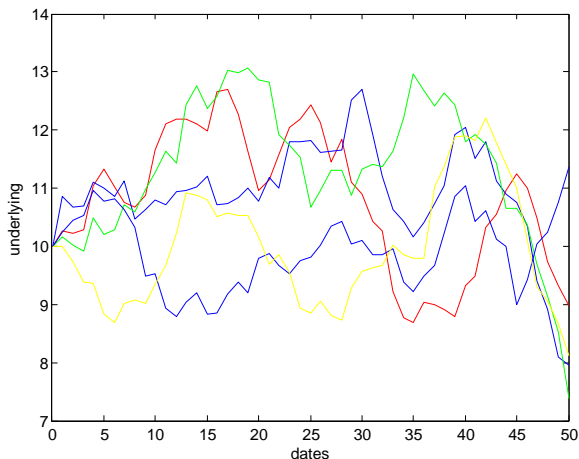


Figure: Typical paths of the underlying stock price which lead to large hedging loss

Thank You